"Hidden" Momentum in an Isolated Brick?

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1 Problem

The term "hidden" momentum was popularized by Shockley [1] in considerations of an electromechanical example, and essentially all subsequent use of this term has been for such examples, where one considers the system to consist of matter plus electromagnetic fields.

A definition of "hidden" momentum has been proposed [2] (see also [3]) which can be applied to mechanical systems as well, where a subsystem has a specified volume and can interact with the rest of the system via contact forces and/or transfer of mass/energy across its surface (which can be in motion),

$$
\mathbf{P}_{\text{hidden}} \equiv \mathbf{P} - M\mathbf{v}_{\text{cm}} - \oint_{\text{boundary}} (\mathbf{x} - \mathbf{x}_{\text{cm}}) (\mathbf{p} - \rho \mathbf{v}_b) \cdot d\mathbf{A} \mathbf{r} \mathbf{e} \mathbf{a} = -\int \frac{f^0}{c} (\mathbf{x} - \mathbf{x}_{\text{cm}}) d\text{Vol}, \quad (1)
$$

where **P** is the total momentum of the subsystem, $M = U/c^2$ is its total "mass", U is its total energy, c is the speed of light in vacuum, \mathbf{x}_{cm} is its center of mass/energy, $\mathbf{v}_{cm} = d\mathbf{x}_{cm}/dt$, **p** is its momentum density, $\rho = u/c^2$ is its "mass" density, u is its energy density, \mathbf{v}_b is the velocity (field) of its boundary, and,

$$
f^{\mu} = \frac{\partial T^{\mu\nu}}{\partial x^{\nu}},\tag{2}
$$

is the 4-force density due to the subsystem, with $T^{\mu\nu}$ being the stress-energy-momentum 4-tensor of the subsystem.

Consider an isolated (unstressed) brick in an inertial frame where it has constant velocity $v \hat{\mathbf{x}}$ parallel to, say, its longest dimension l. In this frame the brick has mass m. The total "hidden" momentum of this brick is zero, so consider a partition of the brick into two subsystems by an imaginary, moving surface, $x_{\text{boundary}} = a + ut$ for $0 < a < l$, while the brick extends over $vt < x < l + vt$. What is the "hidden" momentum in the portion of the brick at $0 < x < a$ at time $t = 0$?

2 Solution

Labeling the subsystem at $vt < x < a + ut$ by the subscript _a, its time-dependent mass is,

$$
m_a = \frac{a + (u - v)t}{l}m.
$$
\n(3)

The time-dependent momentum of this subsystem is,

$$
\mathbf{P}_a = m_a v \,\hat{\mathbf{x}}.\tag{4}
$$

The center of mass of the subsystem has x-coordinate (for times when the boundary surface is within the brick),

$$
x_{a,\text{cm}} = vt + \frac{a + (u - v)t}{2},
$$
\n(5)

and the velocity of the center of mass is,

$$
\mathbf{v}_{a, cm} = \frac{\mathbf{u} + \mathbf{v}}{2} \,. \tag{6}
$$

Thus,

$$
\mathbf{P}_a - m_a \mathbf{v}_{a,\text{cm}} = m_a \left(\mathbf{v} - \frac{\mathbf{u} + \mathbf{v}}{2} \right) = \frac{ma(\mathbf{v} - \mathbf{u})}{2l},\tag{7}
$$

which is nonzero for unless $u = v$.

We now evaluate the "hidden" momentum at time $t = 0$ according to the first form of eq. (1). The boundaries in x of subsystem a at this time are at $x = 0$ and a, with velocities v and u, while $x_{a,\text{cm}}(0) = a/2$:

$$
\mathbf{P}_{\text{a,hidden}} = \mathbf{P}_a - m_a \mathbf{v}_{\text{a,cm}} + \left(0 - \frac{a}{2}\right) \frac{m}{l} (\mathbf{v} - \mathbf{v}) - \left(a - \frac{a}{2}\right) \frac{m}{l} (\mathbf{v} - \mathbf{u})
$$

=
$$
\frac{ma}{2l} (\mathbf{v} - \mathbf{u}) - \frac{ma}{2l} (\mathbf{v} - \mathbf{u}) = 0.
$$
 (8)

To use the second form of eq. (1), we note that $T^{00} = mc^2/Al$ and $T^{0x} = mcv/Al$ are constant within subsystem a, whose cross-sectional area is A, while $T^{0y} = 0 = T^{0z}$ everywhere. The time component f^0 of the 4-force density (2) is,

$$
f^{0} = \partial_{0} T^{00} + \partial_{i} T^{0i} = \frac{\partial T^{00}}{\partial c t} + \frac{\partial T^{0x}}{\partial x}.
$$
\n(9)

The time dependence of T^{00} of subsystem a is due only to the presence of its moving boundaries, $x = vt$ and $x = a + ut$. Near the "left" boundary, $T^{00}(x, t) = T^{00}(x - vt)$, such that $\frac{\partial T^{00}}{\partial ct} = -(v/c)\frac{\partial T^{00}}{\partial x}$, while near the "right" boundary, $T^{00}(x,t) = T^{00}(x-a-ut)$, such that $\partial T^{00}/\partial ct = -(u/c)\partial T^{00}/\partial x$.

It suffices to complete the calculation of $P_{\text{a},\text{hidden}}$ for $t = 0$, as the result should be independent of time. At $t = 0$, f^0 is nonzero only at/near the boundaries $x = 0$ and $x = a$, so we can split the integration to that over $0 < x < b < a$ and $b < x < a$,

$$
P_{\text{hidden},x}(t=0) = -\int \frac{f^0}{c}(x - x_{\text{cm}}) d\text{Vol} = -\frac{A}{c} \int_0^a dx \, f^0 \left(x - \frac{a}{2}\right)
$$

$$
= \frac{Av}{c^2} \int_0^b dx \, \frac{\partial T^{00}}{\partial x} \left(x - \frac{a}{2}\right) + \frac{Au}{c^2} \int_b^a dx \, \frac{\partial T^{00}}{\partial x} \left(x - \frac{a}{2}\right) - \frac{A}{c} \int_0^a dx \, \frac{\partial T^{0x}}{\partial x} \left(x - \frac{a}{2}\right)
$$

$$
= \frac{Av}{c^2} \left[x T^{00} \Big|_0^b - \int_0^b dx \, T^{00} - \frac{a}{2} [T^{00}(b) - T^{00}(0)] \right]
$$

$$
+ \frac{Au}{c^2} \left[x T^{00} \Big|_b^a - \int_b^a dx \, T^{00} - \frac{a}{2} [T^{00}(a) - T^{00}(b)] \right]
$$

$$
- \frac{A}{c} \left[x T^{0x} \Big|_0^a - \int_0^a dx \, T^{0x} - \frac{a}{2} [T^{0x}(a) - T^{0x}(0)] \right] = 0, \quad (10)
$$

in agreement with eq. (8), taking T^{00} and T^{0x} to have values their nonzero, constant values within the interval $0 \leq x \leq a$. and zero outside this.¹

Thus, according to the calculations (9) and (10), there is no "hidden" momentum in the "all-mechanical" example of an isolated brick, or in subsystems of it defined by moving partitions.

As noted in sec. VI of [4], "hidden" momentum is associated with (sub)systems that have internal motion when "at rest", which is not the case for an isolated brick.

References

- [1] W. Shockley and R.P. James, *"Try Simplest Cases" Discovery of "Hidden Momentum" Forces on "Magnetic Currents"*, Phys. Rev. Lett. **18**, 876 (1967), http://kirkmcd.princeton.edu/examples/EM/shockley_prl_18_876_67.pdf
- [2] D. Vanzella, Private communication, (June 29, 2012).
- [3] K.T. McDonald, *On the Definition of "Hidden" Momentum* (July 9, 2012), http://kirkmcd.princeton.edu/examples/hiddendef.pdf
- [4] D. Babson *et al.*, *Hidden momentum, field momentum, and electromagnetic impulse*, Am. J. Phys. **77**, 826 (2009), http://kirkmcd.princeton.edu/examples/EM/babson_ajp_77_826_09.pdf

¹An analysis of eq. (10) which invokes Heaviside step functions Θ , and Dirac delta functions δ , notes that in the frame where the rod has velocity v, the nonzero components of $T^{0\mu}$ can be written as,

$$
T^{00} = \frac{mc^2}{Al}[\Theta(x - vt) - \Theta(x - a - ut)],
$$
\n(11)

$$
T^{0x} = \frac{mcv}{Al}[\Theta(x - vt) - \Theta(x - a - ut)],
$$
\n(12)

where $\Theta(x) = 1$ for $x > 0$ and $= 0$ for $x < 0$. Then,

$$
\frac{\partial T^{00}}{\partial ct} = -\frac{mc^2}{Al} \left[\frac{v}{c} \delta(x - vt) - \frac{u}{c} \delta(x - a - ut) \right],\tag{13}
$$

$$
\frac{\partial T^{0x}}{\partial x} = \frac{mcv}{Al}[\delta(x - vt) - \delta(x - a - ut)],\tag{14}
$$

$$
P_{\text{hidden},x}(t=0) = -\int \frac{f^0}{c}(x - x_{\text{cm}}) d\text{Vol} = -\frac{A}{c} \int_0^a dx \left(\frac{\partial T(00}{\partial ct} + \frac{\partial T^{0x}}{\partial x}\right)(x - x_{\text{cm}})
$$

$$
= \frac{A}{c} \int_0^a dx \frac{mc^2}{Al} \left[\frac{v}{c}\delta(x) - \frac{u}{c}\delta(x - a)\right](x - a/2) - \frac{A}{c} \int_0^a dx \frac{mcv}{Al} [\delta(x) - \delta(x - a)](x - a/2)
$$

$$
= \frac{ma}{l} \left(-u - \frac{v}{2} + \frac{u}{2}\right) + \frac{mav}{l} = \frac{ma(v - u)}{2l}.
$$
(15)

Note that the result of eq. (15) is the same as $\mathbf{P}_a - m_a \mathbf{v}_{a, cm}$ of eq. (7). Hence, if the boundary integral in the first form of eq. (1) were ignored, the two forms of that expression, according to calculations using delta functions in f^0 , would both lead to the same, nonzero "hidden" momentum in present example.

This author finds the delta functions in the expressions (13)-(14) for the 4-force density f^{μ} *very unappealing physically, and so prefers the analysis in the main text that avoids them, with the implication that there is zero "hidden" momentum in the present example.*